

<b>Course Code:</b>	<b>49050101</b>
<b>Course Name:</b>	<b>Advanced Engineering Mathematics-1</b>
<b>Category of Course:</b>	Core
<b>Prerequisite Course:</b>	UG level course in Engineering Mathematics

Teaching Scheme				
Lecture (L)	Tutorial (T)	Practical (P)	Credit	Total Hours
2	2	0	4	40

Course Objectives	
1	To derive Matrix representation of system of linear equations, linear transformation and concepts of Inner products.
2	To understand the importance of basis and orthogonality in Eigen value and Eigen vector.
3	To develop the skill different types of methods of solving Differential equations.
4	To able to apply different conditions as per requirement in methods Advanced Engineering Mathematics.
5	To able to apply accurate Mathematical methods in real life problems of Mechanical Engineering.

Syllabus			
Unit No.	Topic	Prerequisite Topic	Teaching Hours
01	<b>Basic of Matrix and Linear Algebra</b>	---	04 (10%)
	1.1 Introduction of Matrix and Linear algebra.		
	1.2 Matrices & System of linear equations.		
	1.3 Methods for solving system of linear Equations with geometrical approach.		
02	<b>Vector space &amp; Inner Product space</b>	---	04 (10%)
	2.1 Definition of Vector Space and Its Properties.		
	2.2 Linear combination and basis of Vector spaces.		
	2.3 Introduction to Inner Product Space with properties.		
03	<b>Eigen Vectors and Eigen Values</b>	---	04 (10%)
	3.1 Introduction to Eigen Value and Eigen Vectors		
	3.2 Properties of Eigen Value and Eigen Vectors, Algebraic and Geometric Multiplicity		
	3.3 Diagonalization of Square Matrix		
04	<b>Linear Transformation</b>	---	04 (10%)
	4.1 Definition of Linear transformation with Examples		
	4.2 Types of Linear transformations.		
	4.3 Matrices of Linear Transformation, Kernel and Range of Linear Transformation		
05	<b>Matrix Decomposition and Approximations</b>	---	04 (10%)
	5.1 The Cholesky decomposition		
	5.2 QR factorization		
	5.3 Least squares method		
06	<b>Laplace Transformation</b>	---	04 (10%)
	6.1 Definition of Laplace transform and it's Properties		
	6.2 Inverse Laplace transform and it's Properties		
	6.3 Convolution Theorem with Examples		
07	<b>Fourier Series and Transform</b>	---	04 (10%)
	7.1 Introduction to Fourier series		
	7.2 Fourier Series of Discontinuous Functions		
	7.3 Fourier Sine and Cosine Series		
08	<b>Method to solving Ordinary Differential Equations-I</b>	---	04 (10%)
	8.1 Introduction to Differential Equations and its types.		
	8.2 Formation of Differential Equation.		
	8.3 Methods for solving 1 <sup>st</sup> order ODE.		
09	<b>Method to solving Ordinary Differential Equations-II</b>	---	04 (10%)
	9.1 Method for solving Higher order linear Ordinary Differential Equations.		
	9.2 Initial value problems in Higher order linear Ordinary Differential Equations.		
	9.3 Application of Laplace to solve Higher order linear ODE.		

<b>10</b>	<b>Method to solving Partial Differential Equations</b>		---	<b>04 (10%)</b>
	10.1 Introduction to Partial Differential Equations			
	10.2 Method of Separable Variables to solve PDE.			
	10.3 Introduction of Wave and Heat Equation and their Solutions.			
	10.4 Example's solution of Wave & Heat equations by Fourier Series.			

**Course Outcome**

1	Students will understand fundamentals of Linear Algebra and their geometrical meanings.
2	Students will be able to solve problems in their relevant branch using mathematical methods of linear algebra.
3	Students will be able to apply knowledge of Laplace & Fourier Transform in different fields of mechanical branch.
4	Students will be able to get best accurate solutions Using Approximation methods.
5	Students will be able to develop Ordinary and partial Differential equations in their relevant fields.
6	Students will be able to solve mechanical system problems using IVP & BVP.

**Suggested Reference Books**

1	Bronson, R. "Matrix Operations", Schaum's outline series, 2 <sup>nd</sup> Edition, McGraw Hill, 2011.
2	Advanced Engineering Mathematics by Erwin Kreyszig.
3	O'Neil, P.V., "Advanced Engineering Mathematics ", Thomson Asia Pvt. Ltd., Singapore, 2003.
4	Introduction to Linear Algebra , Strang Gilbert 5th ed. Wellesley, MA: Wellesley-Cambridge Press
5	Differential Equations: Theory, Technique and Practice, G.F. Simmons, S. G. Krantz, Tata Mc GrawHill Publishing, 2007.
6	An introduction to Ordinary Differential Equations, James C. Robinson, Cambridge University Press, New York, 2008 (4th print).
7	Differential Equations and their Applications by M Braun
8	An Introduction to Ordinary Differential Equations by Earl A Coddington and Mathematics
9	Partial Differential Equations by Erich Miersemann Department of Mathematics Leipzig University.

**Proposed Evaluation Scheme by Academicians (Percentage of Weightage out of 100%)**

<b>Theory Descriptive Test</b>	<input type="text"/>	<b>MCQ Test</b>	<input type="text"/>	<b>Hands on Project</b>	<input type="text"/>
<b>Formulas and Derivation Test</b>	<input type="text"/>	<b>Numerical Test</b>	<input type="text"/>	<b>Seminar</b>	<input type="text"/>

**Practical Project/Hands On Project**

Sr. No.	List of Practical Projects	Linked with Unit
1	Identify Matrix Transformation for Image editing features like zooming, scaling, rotating, etc..	Unit 1
2	Define Different Vector space with different Operations.	Unit 2
3	Describe geometric approach of Quadratic form in to Canonical form with example.	Unit 3
4	Derive general form of Projections.	Unit 4
5	Define problems in Least squares method.	Unit 5
6	Find and apply concepts of Laplace Transform in Mechanical branch.	Unit 6
7	Find and apply concepts of Fourier Transform in Mechanical branch	Unit 7
8	Construct one real life 1 <sup>st</sup> order Ordinary Differential Equation	Unit 8
9	Construct one Higher order Ordinary Differential Equation and solve with IVP.	Unit 9
10	Describe Heat equation Solution with different boundary value Problems.	Unit 10